# Visualising actions, computing cost, and fixed price for $G \times \mathbb{Z}$ 

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## Executive summary

The study of essentially free pmp actions $G \curvearrowright(X, \mu)$ of lcsc groups is equivalent to the study of invariant point processes on $G$.

This is due to a fundamental relationship between weakly lacunary sections and point processes. I will explain this equivalence.

In particular, we can exploit this relationship to give the first new technique to compute cost in the nondiscrete case, for $G \times \mathbb{Z}$ and other groups.

## Setup

Throughout, $G$ will be a locally compact second countable (lcsc) group.
We will mostly assume $G$ is nondiscrete, noncompact, and unimodular.
Once a Haar measure $\lambda$ on $G$ is fixed, it is possible to define the cost of essentially free pmp actions $G \curvearrowright(X, \mu)$ on standard Borel spaces by using lacunary sections.

## Lacunary section review

Let $G \curvearrowright X$ be a Borel action on a standard Borel space.
A lacunary section is a Borel subset $Y \subset X$ which meets every orbit, and such that there exists an identity neighbourhood $U \subseteq G$ such that $U y \cap Y=\{y\}$ for all $y \in Y$.

Fact: lacunary sections always exist. (See Kechris for most general statement + history)
This implies $G y \cap Y$ is countable, so the orbit equivalence relation of $G \curvearrowright X$ restricts to a countable Borel equivalence relation $\mathscr{R}_{Y}$ (cber) on $Y$.

If there is a $G$-invariant probability measure $\mu$ on $X$ for which the action $G \curvearrowright(X, \mu)$ is essentially free, then there is a probability measure $\mu_{Y}$ on $Y$ such that $\left(Y, \mathscr{R}_{Y}, \mu_{Y}\right)$ is a quasi-pmp cber (and pmp if $G$ is unimodular). Sometimes called a cross-section equivalence relation.

You can define $\operatorname{cost}(G \curvearrowright(X, \mu))$ to be $\operatorname{cost}\left(Y, \mathscr{R}_{Y}, \mu_{Y}\right)$ (normalised by its intensity).

## The configuration space action $G \curvearrowright \mathbb{M}$

Let $\mathbb{M}=\{\omega \subset G \mid \omega$ is locally finite $\} \subset 2^{G}$, where "locally finite" is with reference to a leftinvariant proper metric on $G$

There is a natural shift action $G \curvearrowright \mathbb{M}$
We equip $\mathbb{M}$ with the smallest $\sigma$-algebra that makes the following point counting functions measurable: for $U \subseteq G$ Borel, define

$$
\left\{\begin{array}{l}
N_{U}: \mathbb{M} \rightarrow \mathbb{N}_{0} \cup\{\infty\} \\
N_{U}(\omega)=|\omega \cap U|
\end{array}\right.
$$



## A lacunary section for $G \curvearrowright \mathbb{M}$ ?

Recall: $\mathbb{M}=\{\omega \subset G \mid \omega$ is locally finite $\}$
The rooted configuration space is $\mathbb{M}_{0}=\{\omega \in \mathbb{M} \mid 0 \in \omega\}$, where $0 \in G$ denotes the identity element.
Observe that if $g \in \omega$, then $0 \in g^{-1} \omega$, and so $g^{-1} \omega \in \mathbb{M}_{0}$. So $G \mathbb{M}_{0}=\mathbb{M} \backslash\{\varnothing\}$, and $\mathbb{M}_{0}$ meets essentially every orbit of $G \curvearrowright \mathbb{M}$.

This calculation also shows that $U \omega \cap \mathbb{M}_{0}=\left\{u^{-1} \omega \mid u \in \omega \cap U\right\}$.
In particular, if $U$ is any bounded identity neighbourhood, then $\left|U \omega \cap \mathbb{M}_{0}\right|$ is always finite for any $\omega \in \mathbb{M}_{0}$.

Thus $\mathbb{M}_{0}$ is a "weakly lacunary" section for $G \curvearrowright \mathbb{M}$. This is the only kind of example that exists.
For "point process actions", weakly lacunary is the natural notion, not lacunary.

## Point process actions

A point process on $G$ is a probability measure $\mu$ on $\mathbb{M}$.
That is, a random discrete subset of $G$.

It is invariant if it is an invariant measure for the action $G \curvearrowright \mathbb{M}$.

Speaking more properly, a point process is a random element $\Pi \in \mathbb{M}$. I will try avoid this random element terminology.

## Point process examples

- Lattice shifts. If $\Gamma<G$ is a lattice, then view $G / \Gamma$ as a subset of $\mathbb{M}$
- The Poisson point process. It is the nondiscrete analogue of Bernoulli percolation $\operatorname{Ber}(p)=\left(p \delta_{1}+q \delta_{0}\right)^{\otimes \Gamma}$ on $\{0,1\}^{\Gamma}$
- Every lacunary section $Y \subset X$ of a free pmp action $G \curvearrowright(X, \mu)$ naturally induces an "orbit viewing factor map" $V: X \rightarrow \mathbb{M}$ (next slide), and the push forward measure $V_{*} \mu$ is an invariant point process

Fact: Every free pmp action is isomorphic to a point process. (More generally, nonfree actions are some kind of "bundle of point processes")

## Visualising lacunary sections

Fix a lacunary section $Y \subset X$ for a free action $G \curvearrowright X$.
We identify each orbit $G x$ with $G$ via $g \mapsto g x$.

We study orbit intersections $G x \cap Y$ under this identification. Formally, define the orbit viewing map $V: X \rightarrow 2^{G}$ by
$V(x):=\left\{g \in G \mid g^{-1} x \in Y\right\}$ (the inverse makes it equivariant)
By the lacunary property, $V$ takes values in $\mathbb{M}=\{\omega \subset G \mid \omega$ is locally finite $\}$.
Observe that $Y=V^{-1}\left(\mathbb{M}_{0}\right)$ : since $0 \in V(x)$ iff $x \in Y$.

In short: a choice of lacunary section induces a factor map $X \rightarrow \mathbb{M}$, and we recover the lacunary section as the pre-image of the canonical section $\mathbb{M}_{0}$.

## Current state

- A choice of lacunary section $Y \subset X$ for a free action $G \curvearrowright(X, \mu)$ induces a factor map $V: X \rightarrow \mathbb{M}$ and hence an invariant point process $V: \mu$
- With some work, you can construct a Borel injection $\mathscr{V}: X \rightarrow \mathbb{M}$, and hence $G \curvearrowright(X, \mu)$ and $G \curvearrowright(\mathbb{M}, \mathscr{V} * \mu)$ are isomorphic actions

For this reason, I will now speak just of point process actions.

## The Palm equivalence relation

If $\mu$ is an invariant point process "of finite intensity", then there is a natural measure $\mu_{0}$ on the weakly lacunary section $\mathbb{M}_{0}$ such that $\left(\mathbb{M}_{0},\left.\mathscr{R}\right|_{\mathbb{M}_{0}}, \mu_{0}\right)$ is a quasi-pmp cber (and pmp if $G$ is unimodular), where $\mathscr{R}$ is the orbit equivalence relation of $G \curvearrowright \mathbb{M}$.

The measure $\mu_{0}$ comes from probability theory and is known as the Palm measure and we call $\left(\mathbb{M}_{0},\left.\mathscr{R}\right|_{M_{0}}, \mu_{0}\right)$ the Palm equivalence relation of $\mu$.

It admits a reasonably simple algebraic definition, but I will use Palm-free definitions for interests of time.

If you are familiar with cross-section equivalence relations, it's the same thing (more elegant imo)
To define cost I must explain the intensity of a point process, what a graphing of a point process is, and how to measure the size of a graphing.

## Intensity of an invariant point process $G \curvearrowright(\mathbb{M}, \mu)$

Recall that for $U \subseteq G$ the function $\left\{\begin{array}{l}N_{U}: \mathbb{M} \rightarrow \mathbb{N}_{0} \cup\{\infty\} \\ N_{U}(\omega)=|\omega \cap U|\end{array}\right.$ is measurable.
Fix $U \subseteq G$ with $0<\lambda(U)<\infty$, and define intensity $(\mu):=\frac{1}{\lambda(U)} \int_{\mathbb{M}}|\omega \cap U| d \mu(\omega)=\frac{\mathbb{E}_{\mu}\left[N_{U}\right]}{\lambda(U)}$
Because $\mu$ is invariant, the function $U \mapsto \int_{\mathbb{M}}|\omega \cap U| d \mu(\omega)$ defines a right invariant Haar measure on $G$, which shows that the intensity is well-defined. It scales linearly with the choice of Haar measure.

## Examples

- A process has zero intensity if and only if it is trivial (that is, $\mu=\delta_{\varnothing}$ )
- The intensity of a lattice shift $G \curvearrowright G / \Gamma$ is $1 / \operatorname{covol}(\Gamma)$


## Factor graphs: the analogue of graphings

The distance- $R$ factor graph on $\omega \in \mathbb{M}$ has vertex set $\omega$ and edge set

$$
\mathscr{D}_{R}(\omega)=\{(g, h) \in \omega \times \omega \mid d(g, h)<R\}
$$

Note that it is deterministic given the input It's equivariantly defined: $\mathscr{D}_{R}(g \omega)=g \mathscr{D}_{R}(\omega)$ (we use a metric which is left-invariant)


## Factor graphs, formally

Let $\operatorname{Graph}(G)$ denote the space of abstractly embedded graphs in $G$. Formally, $\operatorname{Graph}(G)=\left\{(V, E) \in \mathbb{M}(G) \times \mathbb{M}(G \times G) \mid E \subseteq V \times V\right.$ and $\left.E=E^{-1}\right\}$

It is a $G$-space in its own right. A (Borel) factor graph is a measurable and equivariant map $\mathscr{G}: \mathbb{M}(G) \rightarrow \operatorname{Graph}(G)$ such that the vertex set of $\mathscr{G}(\omega)$ is $\omega$.

## The average degree of a factor graph

Let $\mu$ be an invariant point process and $\mathscr{G}$ a factor graph. The average degree of $\mathscr{G}$ (with respect to $\mu$ ) is
$\overleftrightarrow{\mu}_{0}(\mathscr{G})=\frac{1}{2} \int_{\mathbb{M}_{g \in U \cap \omega}} \operatorname{deg}_{\mathscr{G}(\omega)}(g) d \mu(\omega)=\frac{1}{2} \mathbb{E}\left[\sum_{g \in U \cap \omega} \operatorname{deg}_{\mathscr{G}(\omega)}(g)\right]$

where $U \subseteq G$ is any set of unit volume.

## Cost

The cost of an invariant point process $\mu$ is defined by

$$
\operatorname{cost}(\mu)-1=\inf _{\mathscr{G}}\left[\overleftrightarrow{\mu_{0}}(\mathscr{G})-\text { intensity }(\mu)\right]
$$

where the infimum ranges over all connected factor graphs $\mathscr{G}$
It's not immediately apparent from the above formula, but (cost -1 ) scales with the choice of Haar measure $\lambda$

For lattice shifts, $\operatorname{cost}(G \curvearrowright G / \Gamma)-1=\frac{d(\Gamma)-1}{\operatorname{covol}(\Gamma)}$, where $d(\Gamma)$ denotes the rank of $\Gamma$ (minimum size of a generating set)

## Cost vs. factors

If $\Phi: \mathbb{M} \rightarrow \mathbb{M}$ is a factor map and $\mu$ is a point process, then $\operatorname{cost}(\mu) \leq \operatorname{cost}\left(\Phi_{*} \mu\right)$

In particular, the cost is an isomorphism invariant (can show it's an OE invariant in an appropriate sense)

This follows from Gaboriau's induction formula for cost (you can also prove it directly)

## Factor of IID cost

I stress that factor graphs should be deterministically defined.
A (perhaps less well-known?) fact is that, as far as computing the cost is concerned, you're allowed to add factor of IID randomness.

## Discrete example [Tucker-Drob]

If $\Gamma \curvearrowright^{\alpha}(X, \mu)$ is a free pmp action and $\Gamma \curvearrowright^{\beta}[0,1]^{\Gamma}$ is the Bernoulli shift, then $\alpha$ is weakly equivalent to $\alpha \times \beta$. In particular, $\operatorname{cost}(X, \mu)=\operatorname{cost}\left(X \times[0,1]^{\Gamma}\right)$. That is, the cost of a free action is equal to the cost of its Bernoulli extension.

This should be true for any pmp cber (Abért-M. prove it for point processes).
If $\mu$ is any free point process, then it has the same cost as its Bernoulli extension $[0,1]^{\mu}$
Corollary: the Poisson point process has maximal cost (since it's a factor of any Bernoulli extension)

## Bernoulli extensions

If $(X, \mathscr{R}, \mu)$ is a pmp cber, then it admits a class bijective Bernoulli extension $(\widetilde{X}, \widetilde{\mathscr{R}}, \widetilde{\mu}) \rightarrow(X, \mathscr{R}, \mu)$

Formally:

- $\widetilde{X}$ consists of pairs $(x, f)$ where $x \in X$ and $f:[x]_{\mathscr{R}} \rightarrow[0,1]$ is a labelling of its equivalence class
- We declare $(x, f) \widetilde{\mathscr{R}}\left(x^{\prime}, f^{\prime}\right)$ if $x \mathscr{R} x^{\prime}$ and $f=f^{\prime}$
- For $A \subseteq \widetilde{X}$, we set $\widetilde{\mu}(A)=\int_{X} \eta_{x}(A) d \mu(x)$, where $\eta_{x}=\operatorname{Leb}^{[x]_{\mathcal{A}}}$


## Informally

It's $X$ but every point $x \in X$ has IID Unif[0,1] labels on the points of its equivalence class

## IID markings of point processes

In general, every class bijective extension $\left(\widetilde{Y}, \widetilde{R}, \widetilde{\mu_{Y}}\right) \rightarrow\left(Y, \mathscr{R}, \mu_{Y}\right)$ of a lacunary section arises as a lacunary section of an extension $G \curvearrowright(\widetilde{X}, \mu) \rightarrow G \curvearrowright(X, \mu)$

In particular, every point process $\mu$ has a Bernoulli extension or IID marking, which I will denote by $[0,1]^{\mu}$.

## Informal example:\{H, T\}-IID of a point process $\mu$

First sample the process...


## Informal example:\{H, T\}-IID of a point process $\mu$

First sample the process...

...then each point independently tosses a coin heads or tails

## The $\Xi$-configuration space action $G \curvearrowright \Xi^{\mathbb{M}}$

Let $\Xi$ denote a complete separable metric space of marks (think of \{Heads, Tails\} or [0,1]).
A $\Xi$-marked configuration is a discrete subset $\omega$ of $G$ where every point is labelled by an element of $\Xi$. Formally, let
$\Xi^{\mathbb{M}}=\left\{\omega \in \mathbb{M}(G \times \Xi) \mid\right.$ if $(g, \xi) \in \omega$ and $\left(g, \xi^{\prime}\right) \in \omega$ then $\left.\xi=\xi^{\prime}\right\}$
A $\Xi$-marked point process is a probability measure on $\Xi^{\mathbb{M}}$.
If $\mu$ is a point process on $G$, then its Bernoulli extension is a $[0,1]$-marked point process denoted $[0,1]^{\mu}$ which arises as the Bernoulli extension of the Palm equivalence relation $\left(\mathbb{M}_{0},\left.\mathscr{R}\right|_{M_{0}}, \mu_{0}\right)$

Informally: sample from $\mu$, then at each point put an IID Unif[0,1] number.

## $G \times \mathbb{Z}$ has fixed price one

Visualise $G \times \mathbb{Z}$ as an infinite stack of pancakes (or palacsinták, or crêpes, as you prefer)


## At least some processes have cost one...

Vertical processes



If $\mu$ is any process on $G$, then $[0,1]^{\Delta_{\Delta, \mu}}$ has cost one

## The cost of Bernoulli extensions of vertical processes



Vertical edges

$\varepsilon$-Percolate any horizontal graphing

## Fixed price proof outline

- If $\mu$ is an invariant point process on $G \times \mathbb{Z}$, then its cost is equal to the cost of its Bernoulli extension $[0,1]^{\mu}$
- Any Bernoulli extension $[0,1]^{\mu}$ weakly factors onto some vertical process $\nu$ (and onto its Bernoulli extension $[0,1]^{\nu}$ )
- Cost is monotone for (certain) "weak factors"

Thus $\operatorname{cost}(\mu)=\operatorname{cost}\left([0,1]^{\mu}\right) \leq \operatorname{cost}\left([0,1]^{\nu}\right)=1$.

## Weak factoring

A point process $\mu$ weakly factors onto a process $\nu$ if there is a sequence of factor maps $\Phi^{n}: \mathbb{M} \rightarrow \mathbb{M}$ such that $\Phi_{*}^{n}(\mu)$ weakly converges to $\nu$

Inspired by weak containment (can probably make this formal)
A sequence of point processes $\mu^{n}$ weakly converges to $\mu$ if

$$
\lim _{n \rightarrow \infty} \int_{\mathbb{M}} f(\omega) d \mu_{n}(\omega)=\int_{\mathbb{M}} f(\omega) d \mu(\omega)
$$

for all continuous and bounded functions $f: \mathbb{M} \rightarrow \mathbb{R}_{\geq 0}$ with bounded support

## The topology on M...

...is determined by sequences.
A configuration $\omega^{\prime}$ is an $(R, \varepsilon)$-wobble of $\omega$ if they are bijectively equivalent in $B(0, R)$ by a bijection
$\sigma: \omega^{\prime} \cap B(0, R) \rightarrow \omega \cap B(0, R)$ that moves points by at most $\varepsilon$ - that is, $d(x, \sigma(x))<\varepsilon$

A sequence $\omega_{n}$ converges to $\omega$ if there exists $R_{n} \nearrow \infty$ and $\varepsilon \searrow 0$ such that $\omega_{n}$ is an $\left(R_{n}, \varepsilon_{n}\right)$-wobble of $\omega$


## Weak factoring onto a vertical process

Recall that $\mu$ is some process on $G \times \mathbb{Z}$.
We wish to weakly factor its Bernoulli extension $[0,1]^{\mu}$ onto some vertical process.
We take sparser and sparser subsets of $\mu$ and stretch them.

I call this propagation.
Formally, for $\omega \in[0,1]^{\mathrm{M}(G \times \mathbb{Z})}$, define
$\omega^{1 / n}=\left\{g \in \omega \mid \xi_{g}<1 / n\right\}$, and
$\omega+1=\{(g, l+1) \in G \times \mathbb{Z} \mid(g, l) \in \omega\}$, and
$\Phi^{n}(\omega)=\omega^{1 / n} \cup\left(\omega^{1 / n}+1\right) \cup \cdots \cup\left(\omega^{1 / n}+n-1\right)$

The propagation factor map


The propagation factor map


The propagation factor map
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The propagation factor map


## Extensions

- Similar argument covers $G \times \mathbb{R}$
- Modification using Følner sets proves groups containing noncompact amenable normal subgroups have fixed price one
- Can handle $G \times \Lambda$, where $\Lambda$ is a f.g. group containing an $\infty$ order element


## Question

Do groups of the form $G \times H$ have fixed price one if $H$ contains an $\infty$ order element generating a discrete subgroup?

Would have interesting ramifications for rank gradient in $\mathrm{SL}_{2}(\mathbb{R}) \times \mathrm{SL}_{2}(\mathbb{R})$.

Replacements...

## Replacements...

There is an effort to replace all this point process theory by ultrapowers.
Fin.

